SECTION 1

This section covers both the basic technical information governing bearing selection and the part numbering system used in this catalog. When the part numbering is different from the basic system, that particular numbering is described in the pertinent section. The various ball bearing parts and components referred to in this catalog are illustrated with brief descriptions, the basic dimensional symbols shown are defined.

Basic Information

Basic Technical Information									1-2
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BASIC TECHNICAL INFORMATION

BEARING SELECTION

There are several important considerations which must be evaluated simultaneously when choosing the proper bearing for a particular device. A detailed analysis of these considerations may be found in the Engineering Section; we will, however, briefly discuss some of the more important ones here.

Miniature and instrument ball bearings are normally made of either Stainless Steel or Chrome Alloy Steel. The load ratings listed in this catalog are for chrome steel unless otherwise noted. Load ratings are affected by bearing material. Life calculations are affected by bearing material as well as lubrication selection. These issues are discussed further beginning on page 4-12.

ABEC GRADE

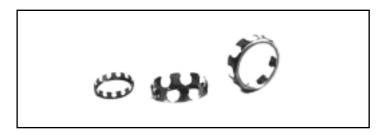
Factors to be considered in selecting the ABEC Grade required for a bearing are Bore and O.D. fits, radial and axial runout requirements, and cost. The table below shows Bore and O.D. radial runout limits and size tolerances vs. ABEC Grade.

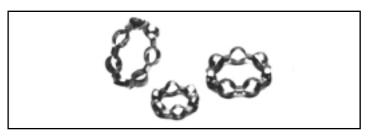
		IMUM RUNOUT	N	MEAN DIAMETE TOLERANCE	R
ABEC GRADE	INNER RING	OUTER RING	BORE	0.D.	O.D.SIZE
1	.0003	.0006	+.0000 0003	+.0000 0003 +.0000 00035	0-18mm over 18- 30mm
3	.0002	.0004	+.0000 0002	+.0000	0-30mm
5	.00015	.0002	+.0000 0002	+.0000	0-30mm
7	.0001	.00015	+.0000 0002	+.0000 0002	0-30mm

The chart on page 4-20 gives a more complete description of the tolerances controlled by the ABEC. Note: A1 miniature and instrument bearings of both the metric and inch configurations meet the tolerances of AMBA Standard 20 for ABEC 1 metric series bearings.

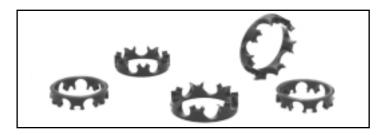
TYPE OF CAGE

The two types of pressed steel ball cages are available for most bearings. "H" or metallic crown type, and "R" or two piece metallic ribbon type.





These two cage types are interchangeable in most common applications.

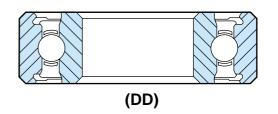


Also available for some sizes are cages made of molded and machined plastics. Our engineers can provide recommendations for any special requirements.

SHIELDS AND SEALS

Shields are available for most sizes, as shown on the listing pages. These closures will help to reduce the entrance of particulate contaminants into the bearing and will reduce the amount of lubricant leakage. Radial clearance between the shield bore and the inner ring 0.D. is approximately .002 to .005 inch. The effect of shields on bearing torque or noise is insignificant.

Contacting seals made of synthetic rubber (DD) are available for most sizes. These seals provide the best protection from the entrance of contaminants, or exit of lubricant, but as a result, significantly increase operating torque. (DD) seals will withstand a slight amount of positive pressure differential.



BASIC TECHNICAL INFORMATION



Non contacting seals made of synthetic rubber (SS), or re-inforced PTFE (LL), are also available for most chassis sizes. This type of seal offers better sealing than a metal shield, while keeping operating torque at the lowest possible levels. (LL) seals will contact the inner ring in some cases, but the nature of the seal material serves to keep torque at a minimum.

RADIAL PLAY

Radial play is the free internal radial looseness between the balls and races. Radial play within a ball bearing is necessary to accommodate thermal expansions, the effects of interference fit, and to control axial play. In cases of extreme temperature, speed, load, or where axial play amount is important, our Engineering Department should be consulted for recommendations.

STARTING AND RUNNING TORQUE

The operating torque of a bearing can be described as starting and running torque. Starting torque is the force required to begin rotation from a bearing at rest. Running torque is the force required to rotate one ring at a known speed while keeping the other ring stationary. The main contributors to bearing torque are seal and lubrication type. For applications in which low starting and/or running torque is required, an Applications Engineer should be contacted for bearing specification recommendations.

STATIC (Cor) AND DYNAMIC (Cr) LOADS

In evaluating the static load conditions, any forces exerted during assembly and test must be considered along with vibration and impact loads sustained during handling, test, shipment and assembly. Dynamic loading includes built-in preload, weight of supported members, and the effect of any accelerations due to vibration or motion changes. The static and dynamic radial load ratings are shown for each chassis size on the product listing pages. Descriptions of these calculated load ratings can be found in the Engineering Information Section.

SPEED OF OPERATION

Although a very large bearing might be the best choice for long life due to its load carrying capacity, it might very well fail early because of damage due to high centrifugal forces or rubbing speeds generated by the rotational velocity. To determine whether a particular bearing will operate satisfactorily at the speed required in a particular device, multiply the value $\frac{\text{Nmax}}{\text{fn}}$ for that bearing by the proper factor taken from the table shown at right. This table takes into account lubricant, retainer type, and ring rotation.

fn vs. Cage, Lubricant Types and Ring Rotation

	Meta	al Cage	Acetal						
		ece or n Type	Crow	n Type	Full Section Type				
Lubricant Ring Rotation	• mner	Outer	Inner	Outer	Inner	Outer			
Petroleum Oil	1.0	0.8	2.0	1.2	4.0	2.4			
Synthetic Oil	1.0	0.8	2.0	1.2	4.0	2.4			
Silicone Oil	0.8	0.7	0.8	0.7	0.8	0.7			
Non-Channeling									
Grease	1.0	0.6	1.6	1.0	1.6	1.0			
Channeling Grease	1.0	0.8	2.0	1.2	2.4	1.6			
Silicone Grease	0.8	0.7	0.8	0.7	0.8	0.7			

Note that the Nmax value should be used for reference only. Higher speeds than specified can be achieved through the accuracy of the device's components. If bearing speed capacity is an important issue, please consult a member of our Engineering Department for assistance.

OPTIMUM LUBRICANT

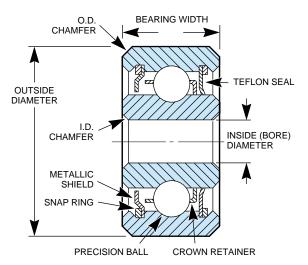
Selection of the lubricant is extremely important. Many lubricants are available for varying conditions and requirements. An NMB Sales or Applications Engineer can help you select the lubricant best suited to your application.

Unless torque is a problem, the selection of a grease is much preferred in prelubricating bearings since it is less susceptible to migration and leakage. Grease can multiply the inherent bearing torque by a factor of 1.2 to 5.0, depending on the type and quantity of grease in the bearing. A discussion of lubrication and a partial listing of our most common greases can be found in the Engineering Information Section.

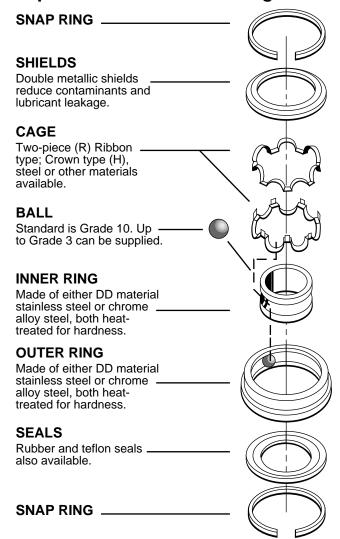
BALL BEARING COMPONENTS

To assist in selecting the bearing with the proper components for a particular design or use, an exploded view of a standard ball bearing with component callouts is shown, below right. To further illustrate the relative positioning of these components in the ball bearing assembly, a cross section, right, is also shown. A detailed discussion of the various components, materials and dimensional tolerances can be found in Section 4, Engineering Information.

Cross section view of ball bearing

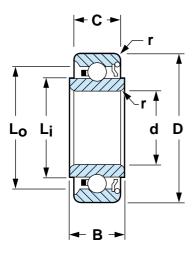


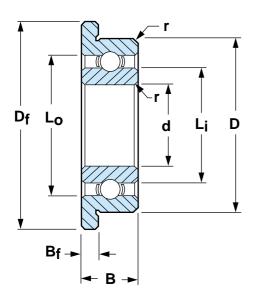
Exploded view of ball bearing



BASIC DIMENSION DATA

The dimensions and their associated symbols used throughout the catalog are described and defined to the right. The listing of these dimensions establish bearing size and other bearing parameters so designers may choose the ball bearing most suited to their requirement.





The Reference Codes shown in the figures below and used throughout this catalog are defined as follows:

Inside Diameter or Bore
O Outside Diameter – O.D.
Inner Ring Width
Outer Ring Width
Flange Outside Diameter
Flange Width or Thickness

L_i Inner Ring Reference Diameter
L_o Outer Ring Reference Diameter

r — Maximum Shaft or Housing Fillet Radius that

bearing corners will clear

Z -----Number of Balls

D_W — Nominal Diameter of Balls **N**_{max} — Maximum Speed (rpm)

f_n ——— Cage and Lubricant Factor. See page 1-3.

PART NUMBERING SYSTEM

EXAMPLE:

DD RIF-418 ZZEE H A7 P25 LY75 KJ R-1350 ZZ R A5 P25 L01 RI-5532 R A7 P25 LO1

GROUP 1	GROUP 2	GROUP 3	GROUP 4	GROUP 5	GROUP 6
MATERIAL	ТҮРЕ	BASIC SIZE	FEATURES	ANDERON METER TEST AND SPECIAL DESIGNS	CAGE
DD	RIF-	418	ZZEE		Н
KJ	R-	1350	ZZ		R
	RI-	5532			R
DD™ = NMB developed stainless steel material which falls within the 400 series Martensitic Stainless Steel grouping. KJ-MKJ3* chrome steel for inner and outer rings. Inner and outer ring material is NMB developed high carbon chromium bearing steel developed for HDDs and other specialty applications. Balls are made of 52100 or equivalent. NO CODE = Chrome alloy steel (52100 or equivalent) *US and foreign patents pending	RI, R, L = Radial ball bearings RIF, RF, LF = Flanged radial ball bearings RI, RIF = Inch Series R, L, RF, LF = Metric Series (exceptions: R-2, R-3, R-4 = inch series)	INCH SERIES First one or two digits indicates O.D. in 16ths of an inch. The following two or three digits indicate the bore size in a fraction of an inch, the first digit being the numerator and the second or the second and third digits being the denominator. METRIC SERIES First two digits indicate O.D. in mm. Second two digits indicate I.D. in mm. SPECIAL SIZE SERIES ZB = Integral shaft AS = Pulley type assemblies; shaft assemblies; mechanical parts; tape guides; special bearings X = Following basic size indicates special ball complement assigned in numerical sequence i.e., X1, X2, etc.	ENCLOSURES Z = Single metallic shield-removable ZZ = Double metallic shield-removable D = Single rubber seal-contact DD = Double rubber seal-contact H = Single metallic shield non-removable HH = Double metallic shield non-removable L = Single glass reinforced PTFE seal-contact LL = Double glass reinforced PTFE seal-contact S = Single rubber seal non-contact SS = Double rubber seal non-contact LZ = Glass reinforced PTFE seal and shield with seal on flange side ZL = Shield and glass reinforced PTFE seal with shield on flange side DZ = Rubber seal and shield EXTENDED INNER RING EE = Both sides	ANDERON METER TEST MT = Motor quality GT = Extremely quiet-H.D.D. spindle motor only No Code = Non- critical application SPECIAL DESIGN SD = Special design bearing	H = Metallic Crown R = Metallic Ribbon J = Acetal crown type MN = Glass fiber reinforced molded nylon M7 = Molded nylon

PART NUMBERING SYSTEM

GROUP 7	GROUP 8	GROUP	9	GROUP 10				
ABEC TOLERANCE	RADIAL PLAY	LUBRICAN	IT	LUBE QUANTITY				
A7	P25	LY75		L				
A5	P25	L01						
A7	P25	L01						
A1 = ABEC 1 A3 = ABEC 3 A5 = ABEC 5 A7 = ABEC 7 Note A1 miniature and instrument bearings of both the metric and inch configurations meet the tolerances of ABMA Standard 20 for ABEC 1 metric series bearings.	P = Followed by two or three numbers indicate the radial play limits in ten thousandths of an inch. Example: P25 indicates radial play of .0002" to .0005"	Lubricant lett followed by a indicate spec LO = Oil LG = Greases LY = Other Oi LD = Dry-No (DD Material	i number to ific type. ils and Greases Lubrication	X = 5-10% L = 10-15% T = 15 -20% No Code = 25-35% H = 40-50% J = 50-60% F = 100% Percentage of void volume				
				IMPORTA	NT NOTE:			
			The NMB numbering system identifies ball bearing size and design. This system is not a guide to create a customized ball bearing. Please use the numbering system to decipher the basic bearing numbers listed in this catalog, or to define a number given to you by a representative of NMB. Bearing numbering systems which are different are explained in the pertinent sections of this catalog. Please consult a member of our Sales or Engineering staff to help you design a new bearing or to interchange another manufacturer's part number.					
			bearing o	or to interchange anoth	ner manufacturer's part	number.		



EXAMPLE:

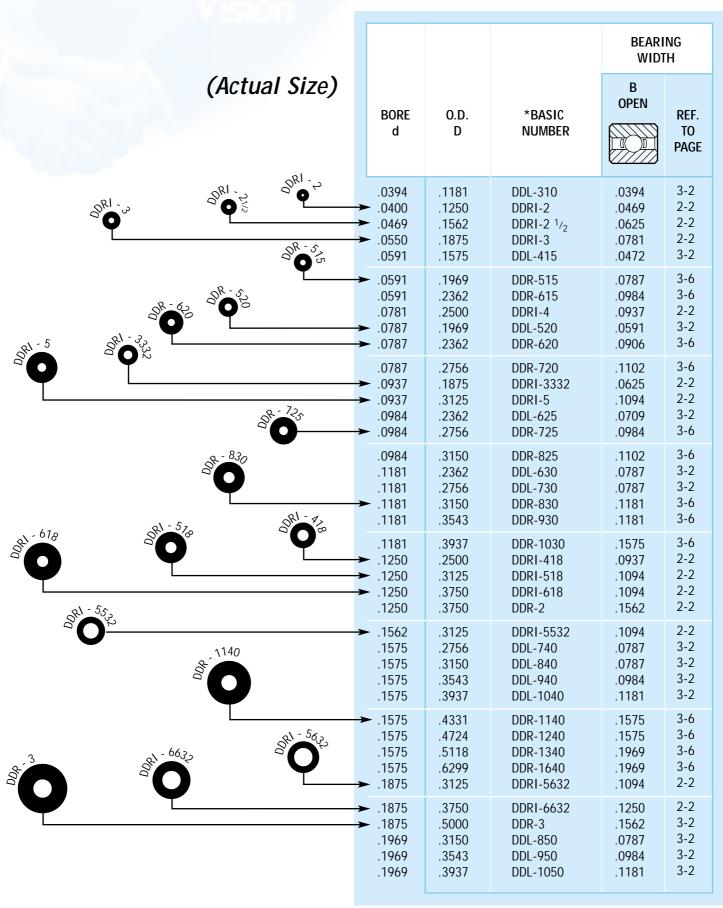
608 DD NR M3 SM A3 LY121 H

ODOLID 4	ODOLID O	ODOLID O	ODOLID 4	ODOLID E	ODOLID (
GROUP 1 BASIC CHASSIS NUMBER	GROUP 2 CAGE	GROUP 3 ENCLOSURE	GROUP 4 EXTERNAL RETAINING RING	GROUP 5 RADIAL PLAY	OROUP 6 NOISE RATING
608	J	DD	NR	M3	SM
See pages 3-10 and 3-11 for listings of Metric 600/6000 Series	J = Molded plastic retainer MN = Glass fiber reinforced molded plastic retainer No Code = Ribbon retainer	Z = Single press type metal shield, non-removable D = Single contact rubber seal S = Single non-contact rubber seal Labyrinth design seal available on some sizes SSD21 = Labyrinth non- contact rubber seal DSD21 = Labyrinth contact rubber seal No Code = Double lip contact rubber seal No Code = Open bearing (Limited Availability) NOTE: Any combination of two enclosure types is available, i.e., ZZ, DD, SS, ZD, DS, ZS.	N = Groove only NR = Groove with retaining ring installed No Code = No groove or retaining ring NOTE: An external retaining ring is used where a flange effect is needed, but where the extra cost and stability of an integral flange are not required. Consult NMB for dimensions.	M2 = 0.003 - 0.008 mm M3 = 0.005 - 0.010 mm M4 = 0.008 - 0.013 mm M5 = 0.013 - 0.020 mm NOTE: Radial play is the internal radial looseness between the balls and the races. Radial play is necessary to accommodate differential thermal expansions, the effects of interference fits and to control axial play.	SM = Vibration critical applications MT = Extremely noise sens tive applications NOTE: Noise codes are the dynamic evaluation of the bearing's performance. By listening to the internal sounds of a bearing in motion (Anderon based testing), NMB can scientifically categorize its bearings into noise levels. By evaluating application needs, the product designer can now coordinate these noise codes and ABEC classes to achieve the most cost effective combination of noise and performance.

NMB METRIC 600/6000 PART NUMBERING SYSTEM

GROUP 7	GROUP 8	GROUP 9
ABEC CLASSES	LUBRICANT	LUBE QUANTITY
A3	LY121	Н
A1 = ABEC 1 A3 = ABEC 3 A5 = ABEC 5 A7 = ABEC 7 NOTE: ABEC classes do not specify noise limits. In certain applications, if runouts and fits are non-critical, it may be possible to achieve the dynamic effects of higher ABEC class bearings by specifying an ABEC 1 bearing with a SM or MT noise code. This could lead to a significant cost savings.	LG20 = Exxon Beacon 325, Synthetic Grease LY48 = Mobil 28 Synthetic Grease LY121 = Kyodo Yushi SRL Synthetic Grease	X = 5-10% L = 10-15% T = 15-20% No Code = 25-35% H = 40-50% J = 50-60% F = 100% Percentage of void volume

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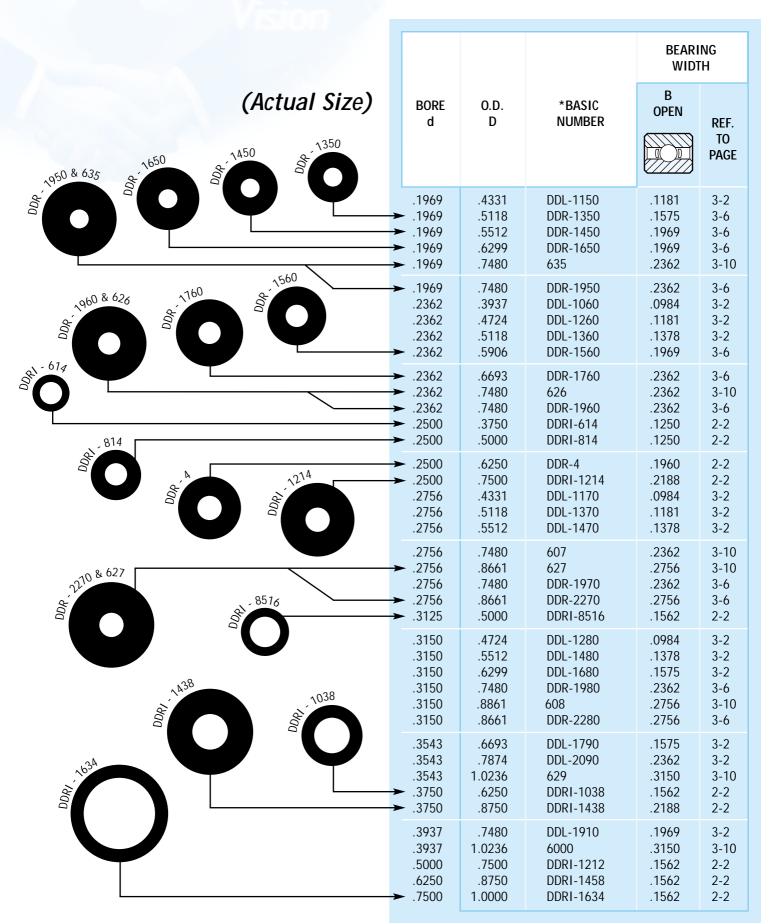
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^{*&}quot;DD" is a trademark of NMB

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